

Data Collection and Management from multiple data sources for PMS feeding

SESSION 3: Predictive maintenance

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Final Event

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Maintaining integrity, performance and safety of the road infrastructure through autonomous robotized solutions and modularization

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1. Introduction

Objectives

- Manage data efficiently

How?

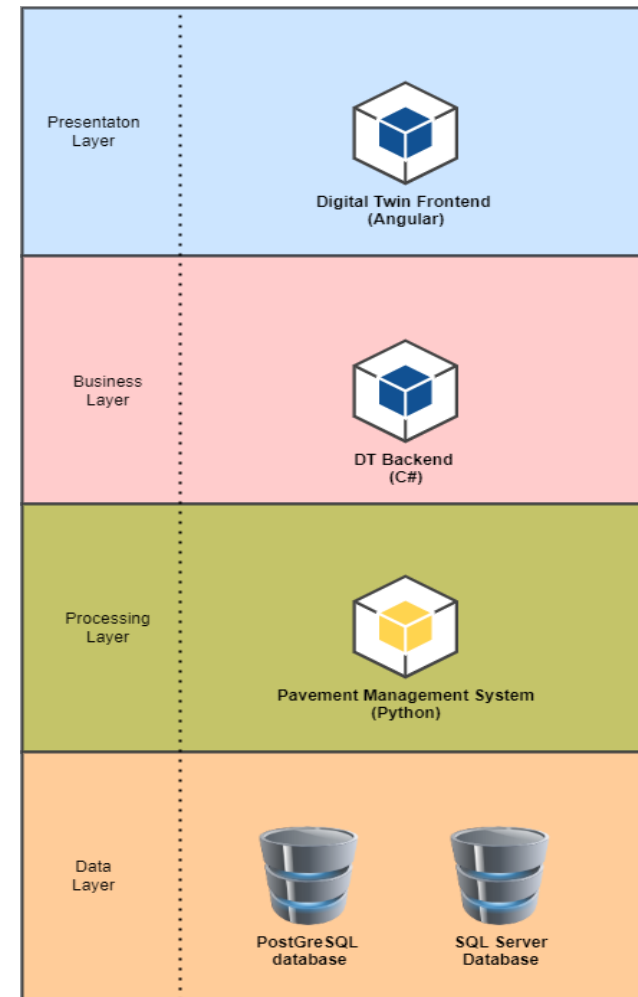
- Identifying data sources and understanding data characteristics
- Implementing an efficient database infrastructure
- Integrating solutions from InfraROB partners
- Communicating components and data



2. InfraROB ICT platform overview

InfraROB PMS components:

- Pavement Management System
- Digital Twin
 - Backend
 - Frontend
- Databases
 - InfraROB geospatial database
 - SQL Server



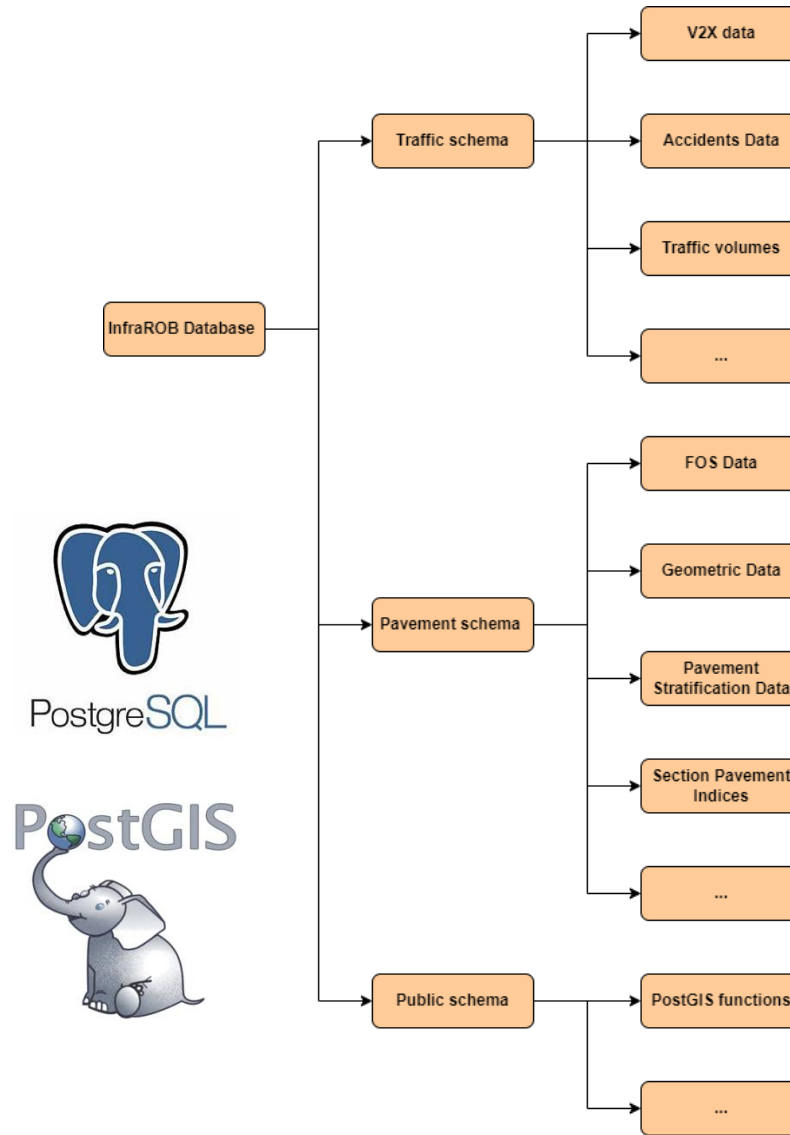
3. InfraROB database

InfraROB Data

- Multiple data sources
- Georeferenced data

Database implementation

- PostgreSQL + PostGIS extension
- Different schemas
- Postgres Functions
- Security



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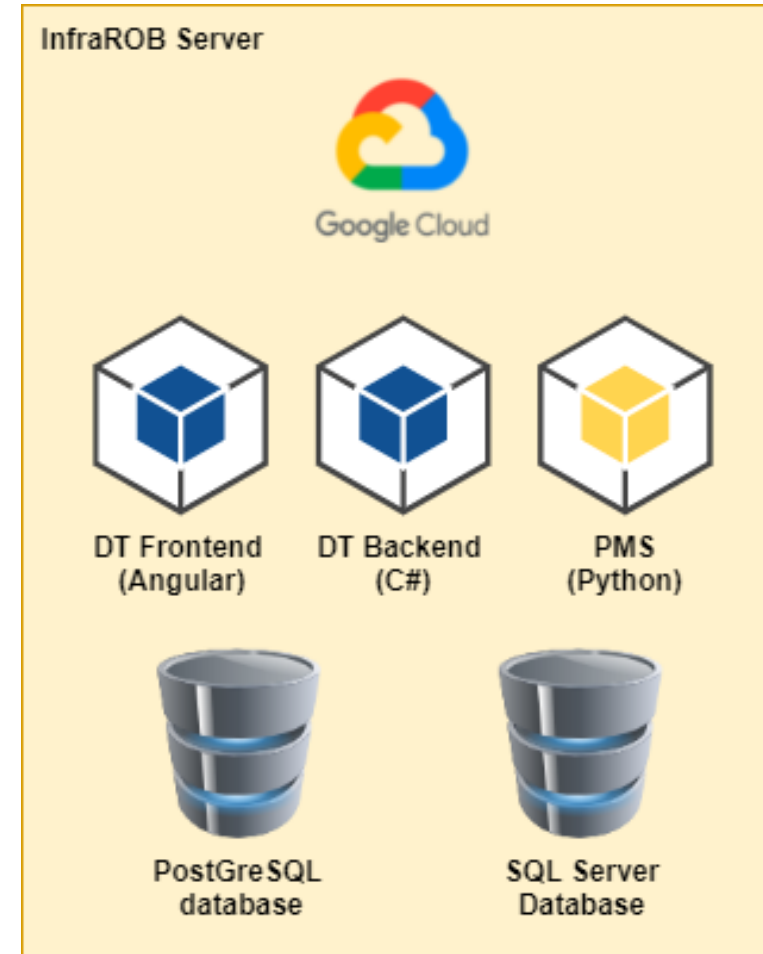
4. InfraROB server

Server requirements

- Components
- Components requirements

Server configuration

- Google Cloud
- Accessibility
- Security



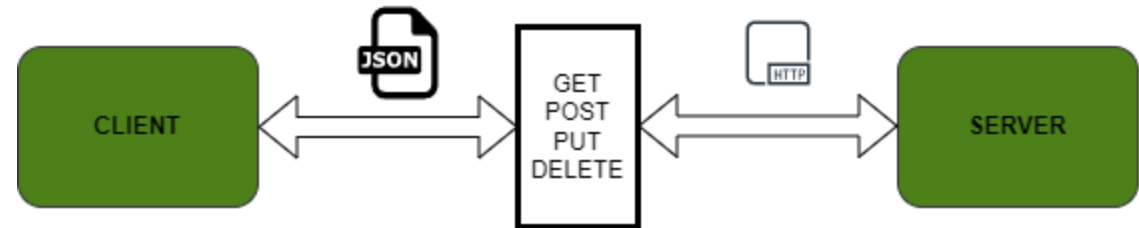
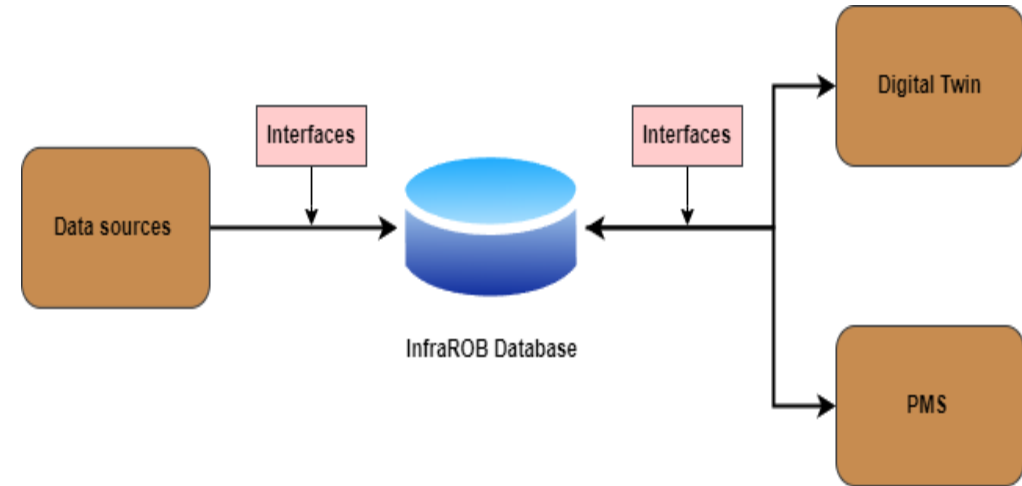
5. Communication interfaces

Objective

- Communicate data sources and applications

Implementation

- Python
- HTTP requests
- JSON
- REST



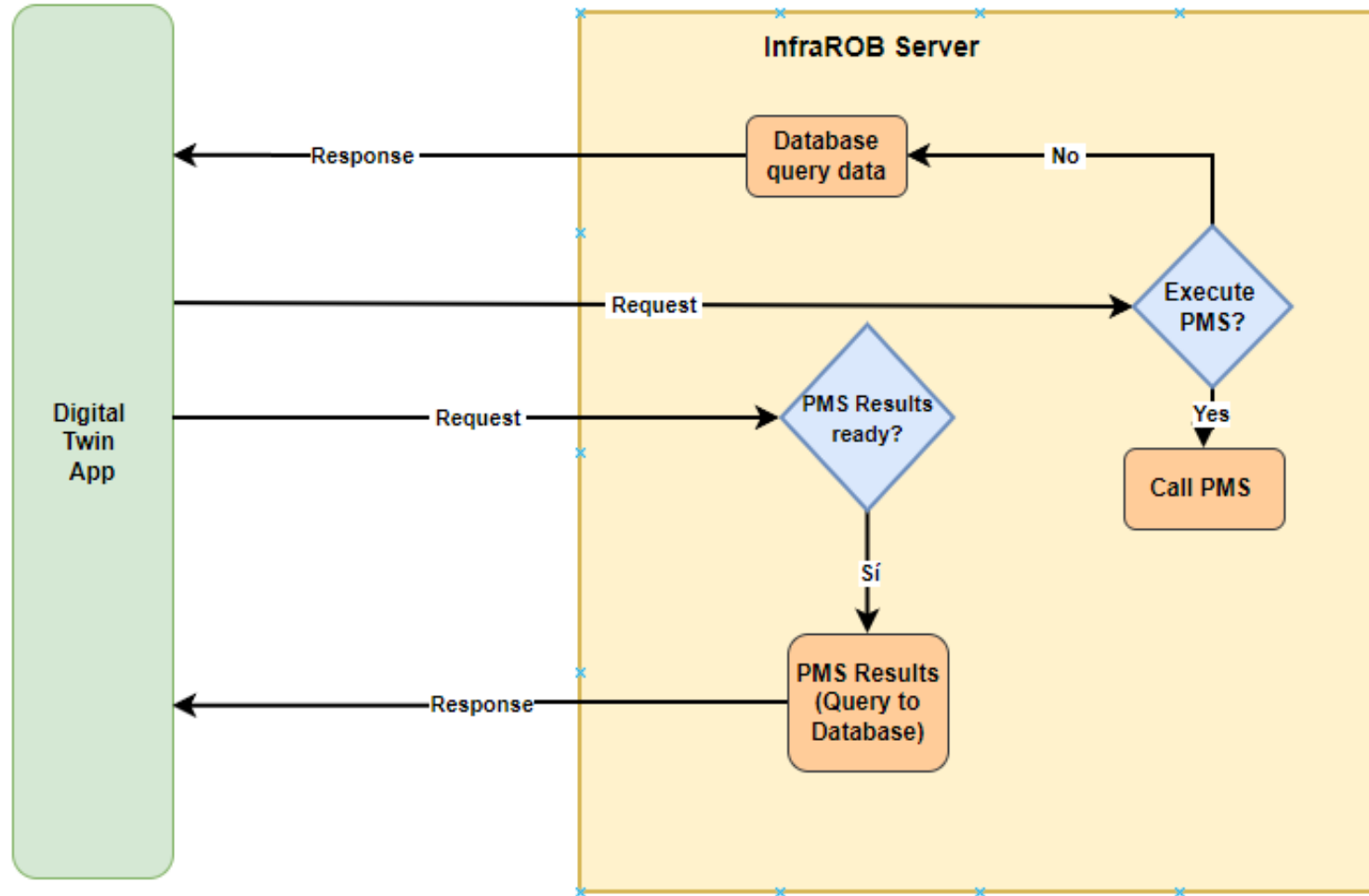
6. DT-PMS communication

Synchronization DT-PMS

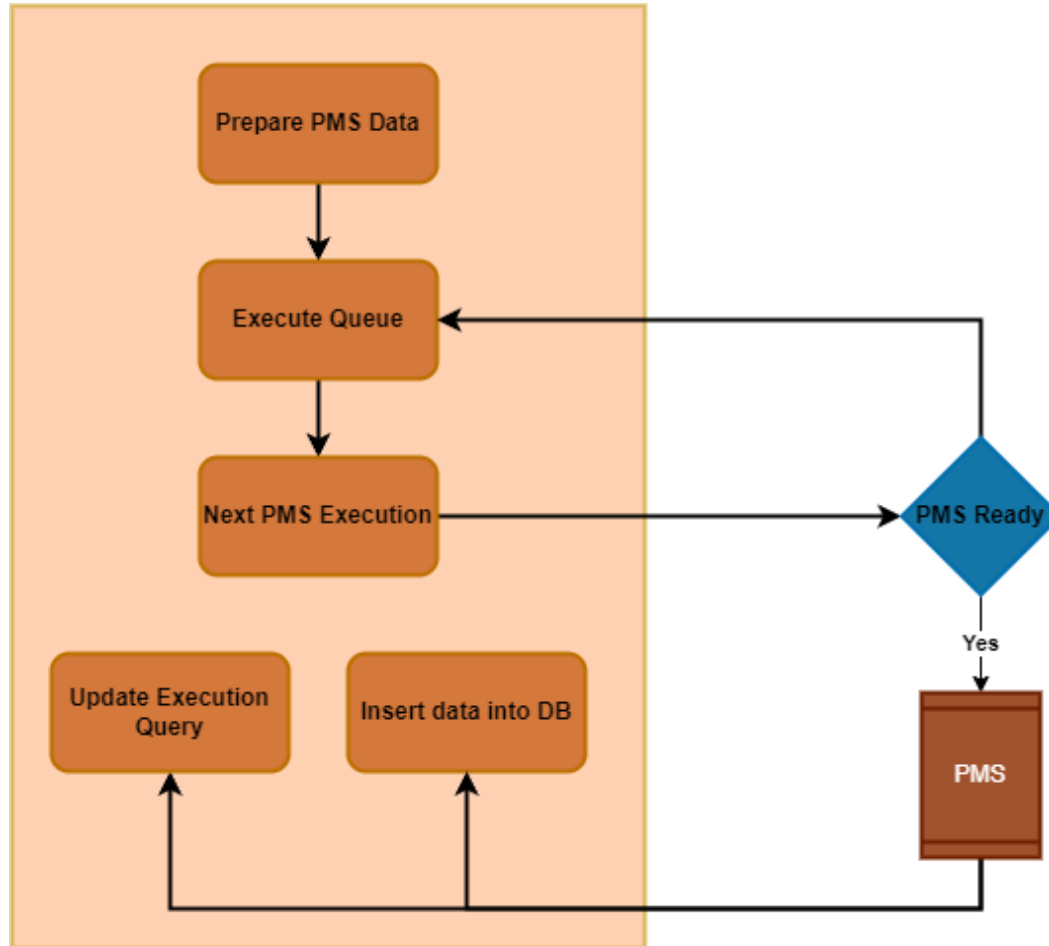
- PMS Execution time
 - From seconds to minutes
- Requirement
 - Not freeze DT – user interaction
- Solution
 - Unsynchronized PMS from DT
 - PMS requests queue



6. DT-PMS communication



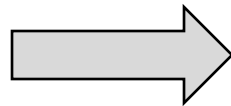
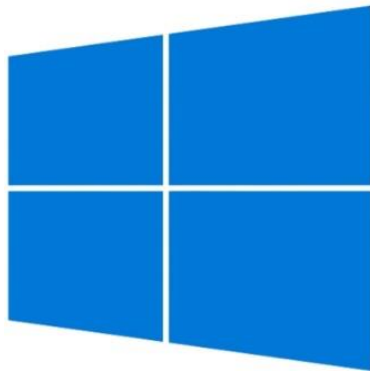
6. DT-PMS communication



7. Components integration

Integration

- Digital Twin → Windows development
- PMS → Python
- Solution: *Docker containers*



8. Results

Validation

- Geospatial database
- Data collection
- Digital Twin and PMS integration
- Communications between database, DT and PMS
- Errors situation



Thank you for your attention



infrarobproject.com



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of the road infrastructure through an autonomous
robotized solutions and modularization*

Project Partners

Universidade de Vigo

TinyMobileRobots



Technology
Arts Sciences
TH Köln

